

Identification and Estimation of Marginal Structural Mean Models with Instrumental Variables

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Outline

Introduction

Potential outcome framework

Randomization

No unmeasured confounders (Rubin et al. 80s)

Sequential Randomization Assumption (Robins '80s/'90s)

Relaxing SRA

Instrumental variables

Main result

Estimation in practice

Remarks on assumptions

Simulation

Closing remarks

A motivating example

Sports argument: Bill Belichick is a great coach: When average players come to play for him, their performance jumps up; when they leave, they become average again.



Causal framework: Players have a potential outcome, their performance under Belichick and not under Belichick. This pre/post comparison approximates the difference between the potential outcomes.

Sports counter-argument: It's not Belichick. He's just been fortunate . . .

Causal framework: The association between Belichick (treatment) and player performance (outcome) is spurious; it exists due to a confounder. Is there some variable associated with treatment and outcome?

Sports counter-counter-argument: But there was one year when the quarterback was injured, and new players that year also performed better than usual.



Causal framework: There are no unmeasured confounders; we can obtain the causal effect by controlling for the known confounder.

We postulate “potential outcomes,” random variables indexed by treatment level

$$Y_a(\omega), a \in \mathcal{A}$$

interpreted as the response of a unit ω if, possibly contrary to fact, treatment level a were applied to ω and related to the observed data by the consistency axiom

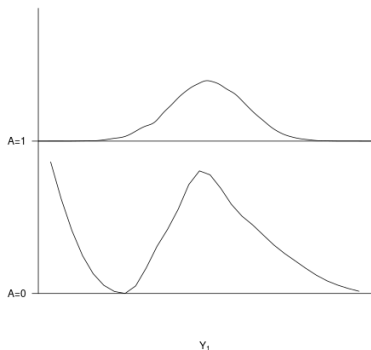
$$Y = Y_A = Y_a|_{a=A}$$

A “causal effect” can then be stated/defined in terms of the potential outcomes, e.g.,

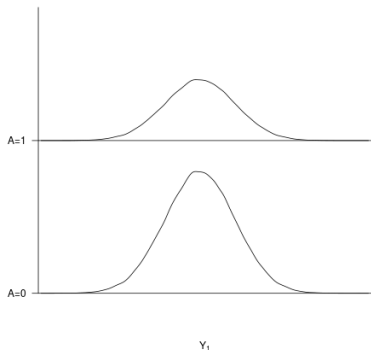
$$\mathbb{E}(Y_1 - Y_0)$$

“Average Treatment Effect”

Can't say much about Y_1 only knowing $Y_1 \mathbb{1}\{A = 1\}$.



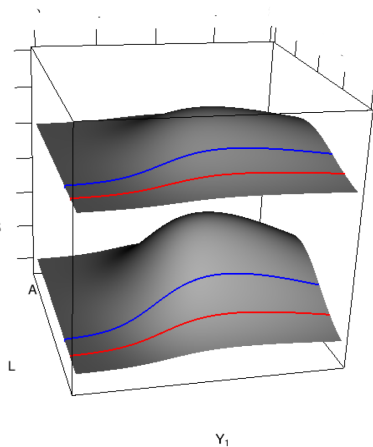
We need to be able to say something about $Y_1 \mathbb{1}\{A = 0\}$ based off of $Y_1 \mathbb{1}\{A = 1\}$



randomization with respect to treatment, $Y_a \perp\!\!\!\perp A$
 recover Y_1 by dividing $Y \mathbb{1}\{A = 1\}$ by $P(A = 1)$
 in general, $\mathbb{E}(g(Y_a)) = \mathbb{E}\left(\frac{g(Y \mathbb{1}\{A=a\})}{f(A)}\right)$

“No Unmeasured Confounders”:
 randomization holds conditional
 on some covariate L . Compute
 $Y_1 | L = l$, the potential outcome
 at each level l , now dividing by
 the conditional treatment
 probability (“propensity”).
 Then integrate over L .

$$\mathbb{E}(g(Y_a)) = \mathbb{E} \left(\frac{\mathbb{1}\{A = a\}g(Y)}{f(A | L)} \right)$$



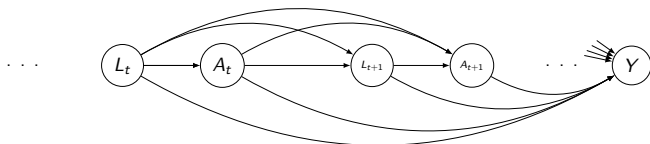
- ▶ (clones/copies interpretation) At any covariate level $L = l$, if say, $P(A = 1 | L = l) = 1/4$, then there are 3 unobserved units for every observed unit and (no unmeasured confounders) these are homogenous as to Y_1
- ▶ (likelihood perspective)

$$\begin{aligned}\mathbb{P}(Y = y, A = a, L = l) &= \mathbb{P}(Y = y | A = a, L = l)\mathbb{P}(A = a | L = l)\mathbb{P}(L = l) \\ &= \mathbb{P}(Y_a = y | A = a, L = l)\mathbb{P}(A = a | L = l)\mathbb{P}(L = l) \text{ (consistency)} \\ &= \mathbb{P}(Y_a = y | L = l)\mathbb{P}(A = a | L = l)\mathbb{P}(L = l) \text{ (NUC)}\end{aligned}$$

$$\begin{aligned}\mathbb{P}(Y_a = y, A = a, L = l) / \mathbb{P}(A = a | L = l) \text{ (positivity)} \\ = \mathbb{P}(Y_a = y, L = l)\end{aligned}$$

Longitudinal setting: estimating the effect of a treatment regime in the presence of time-varying confounding.

Central example: Estimating time to progression to AIDS under HAART: Physician bases treatment on the patient's CD4 count, that treatment affects CD4 count, which in turn informs a subsequent treatment decision. And CD4 count is prognostic of the outcome.



- ▶ T time points $t = 1, \dots, T$
- ▶ Treatment regime $\bar{A} = (A_1, \dots, A_T) \in \mathcal{A}^T$ discrete-valued
- ▶ Potential outcomes $\{Y_{\bar{a}}\}$ indexed by fixed treatment regimes $\bar{a} \in \mathcal{A}^T$
- ▶ Observed outcome $Y = Y_{\bar{A}} = \sum_{\bar{a}} \mathbb{1}\{\bar{A} = \bar{a}\} Y_{\bar{a}}$ (consistency)
- ▶ Covariates $\bar{L} = (L_1, \dots, L_T)$

similar targets such as

$$\beta = \mathbb{E}(Y_{\bar{a}}) - \mathbb{E}(Y_{\bar{0}})$$

or

$$\beta_1 : \mathbb{E}(Y_{\bar{a}}) = \beta_0 + \beta_1 \sum_t a_t$$

(“marginal structural mean models”)

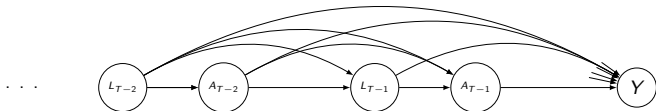
Consider using a regression model to estimate β , e.g.:

$$\mathbb{E}(Y | \bar{A} = \bar{a}) = \mathbb{E}(Y_{\bar{a}} | \bar{A} = \bar{a}) = b_0 + b_1 \sum_t a_t$$

L_{T-1} is a confounder of the subsequent treatment and the outcome, and so should be accounted for, e.g.,

$$\mathbb{E}(Y | \bar{A}, L_{T-1}) = b_0 + \gamma_1 L_{T-1} + b_1 \sum_t A_t$$

on the other hand, controlling for L can block the effect of earlier treatment.



The longitudinal generalization of “no unmeasured confounders” is

- ▶ “Sequential randomization assumption”: for all \bar{a} and t ,

$$Y_{\bar{a}} \perp\!\!\!\perp A_t \mid A_1, \dots, A_{t-1}, L_1, \dots, L_t$$

Propensity score weights generalize to

$$W_{SRA} = \prod_{t=1}^T f_{A_t | \bar{A}_{t-1}, \bar{L}_t}(A_t \mid \bar{A}_{t-1}, \bar{L}_t)$$

SRA will hold when all factors prognostic of Y used by the physicians to determine whether treatment A is given at t are recorded in \bar{A}_{t-1}, \bar{L}_t

A marginal structural mean model (“MSMM”) is a model on the marginal mean of the potential outcomes,

$$\mathbb{E}(Y_{\bar{a}}) = \mu_{\beta}(\bar{a})$$

Besides SRA, also assume $0 < \mathbb{P}(A_t = a \mid \bar{L}_{t-1}, \bar{A}_{t-1}) < 1$ when the conditioning event has positive probability

Then (Robins '98)

$$\mathbb{E}((Y - \mu_{\beta}(\bar{A})) / W_{SRA}) = 0.$$

- ▶ $\hat{\beta}$ asymptotically normal (usual regularity conditions)
- ▶ Standard software routines can be used, as long as they allow observations to be weighted
- ▶ similar change of measure interpretation as NUC theory

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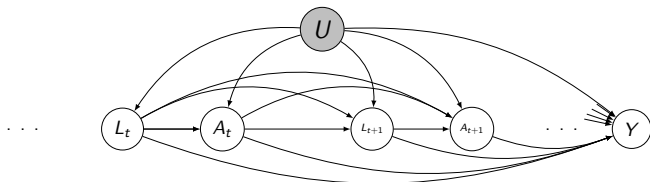
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Suppose there is some unobserved confounder U , which we would need to have observed in order for “SRA” to hold:

$$Y_{\bar{a}} \perp\!\!\!\perp A_t \mid \bar{A}_{t-1}, \bar{L}_{t-1}, \bar{U}_{t-1} \quad \text{for all } t, \bar{a}$$



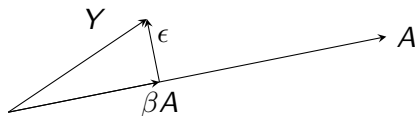
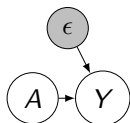
Can we still identify/estimate the causal parameter?

Informally, an IV is a random variable associated with covariates, but orthogonal to the unobserved confounder.

A typical application is OLS with “endogenous error”

$$Y = \beta A + \epsilon$$

Consistency of OLS generally requires ϵ be uncorrelated with A

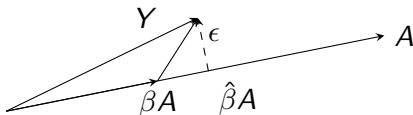
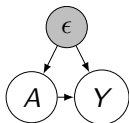


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If in fact the error is correlated with the covariates, OLS is biased

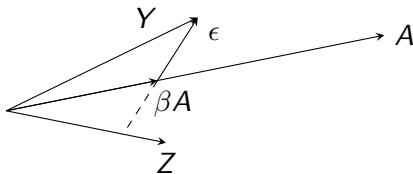
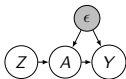


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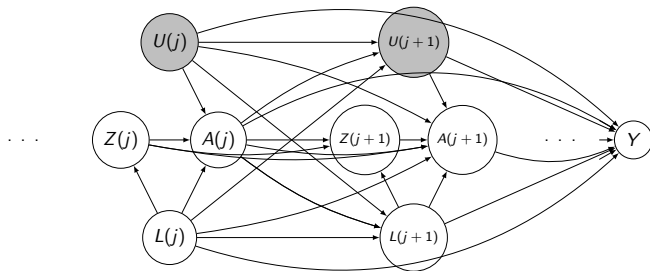
$$Y = \beta A + \epsilon$$

Suppose we have a random variable Z orthogonal to ϵ , but not to A .



Examples of instrumental variables:

- ▶ assignment to treatment
- ▶ physician preference
- ▶ draft status
- ▶ distance to school/hospital



Assumptions

1. $Y_{\bar{a}} \perp\!\!\!\perp A_t \mid \bar{A}_{t-1}, \bar{L}_{t-1}, \bar{U}_{t-1}$ for all t, \bar{a}
2. IV assumptions
 - 2.1 $Y_{\bar{a}\bar{z}} = Y_{\bar{a}}$ a.s. “exclusion restriction”
 - 2.2 $\bar{Z}_t \perp\!\!\!\perp \bar{U} \mid \bar{A}_{t-1}, \bar{Z}_{t-1}, \bar{L}_t$ “IV independence A”
 - 2.3 $\bar{Z} \perp\!\!\!\perp Y_{\bar{a}} \mid \bar{A}, \bar{L}$ “IV independence B”
3. and finally an assumption specific to our problem

3. An assumption specific to our problem, either of:

3.1 Independent Compliance Type:

$$\begin{aligned} & \mathbb{E} [A_t | \bar{U}_t, \bar{L}_t, \bar{A}_{t-1}, \bar{Z}_{t-1}, Z_t = 1] - \mathbb{E} [A_t | \bar{U}_t, \bar{L}_t, \bar{A}_{t-1}, \bar{Z}_{t-1}, Z_t = 0] \\ & = \Delta_t (\bar{L}_t, \bar{A}_{t-1}, \bar{Z}_{t-1}) \end{aligned}$$

or

3.2 Independent Causal Effect (binary treatment only):

$$Y_{(a_t=1, a_{t+1}, \dots, a_T)} - Y_{(a_t=0, a_{t+1}, \dots, a_T)} \perp\!\!\!\perp \bar{U}_t \mid \bar{L}_t, \bar{A}_{t-1}, \bar{Z}_{t-1}$$

Weighted Estimating Equation

Define weights by

$$\bar{W} = \prod_{t=1}^T (-1)^{1-Z_t} \Delta_t (\bar{L}_t, \bar{A}_{t-1}, \bar{Z}_{t-1}) f_{Z_t}(Z_t | \bar{A}_{t-1}, \bar{Z}_{t-1}, \bar{L}_t).$$

Let h denote a vector-valued function of \bar{A} of the same dimension as β . Under the above assumptions,

$$\mathbb{E} (h(\bar{A})(Y - \mu_{\beta}(\bar{A})) / \bar{W}) = \sum_{\bar{a}} h(\bar{a}) (\mathbb{E}(Y_{\bar{a}}) - \mu_{\beta}(\bar{a})) (-1)^{T - \sum_j a_j} = 0$$

where the summation is taken over all tuples $\bar{a} \in \{0, 1\}^{T-1}$

$f_{Z_t|\bar{A}_{t-1}, \bar{Z}_{t-1}, \bar{L}_t}$ and $\Delta_t(\bar{A}_{t-1}, \bar{Z}_{t-1}, \bar{L}_t)$ require modeling/estimation

bootstrap or sandwich variance for inference

weight stabilization analogous to SRA theory

3.1 “independent compliance type”

Interpretation: Z_j assignment to treatment or control A_j the treatment actually received assumption is that the difference in proportions of compliance is accounted for by the observed data

		$A_{Z=0}$	
		0	1
$A_{Z=1}$	0	never-taker	defier
	1	complier	always-taker

3.2 “independent causal effect”

assume A is binary. The assumption implies you could obtain the ATE at a time point, i.e., β_1 in the model

$E(Y_{(\bar{a}_{j-1}, a_j)}) = \beta_0 + \beta_1 a_j$, using non-IV methods. The theorem allows you to go from here to estimating the causal parameter in an arbitrary mean model.

Special case

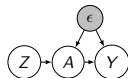
- ▶ $T = 1$ time point
- ▶ A, Z binary
- ▶ $\Delta_j(\bar{L}_j, \bar{A}_{j-1}, \bar{Z}_{j-1}) = \Delta_j(\bar{A}_{j-1})$
- ▶ $f_{Z_j|\bar{A}_{j-1}, \bar{Z}_{j-1}, \bar{L}_j}$ constant

Consider the saturated model

$$\mathbb{E}(Y_a) = \beta_0 + \beta_1 a = \mathbb{E}(Y_0) + (\mathbb{E}(Y_1) - \mathbb{E}(Y_0))a$$

The weights are now $(-1)^{1-Z}$, and

$$\hat{\beta}_1 = \frac{\sum y_t \mathbb{1}\{z_t = 1\} - \sum y_t \mathbb{1}\{z_t = 0\}}{\sum a_t \mathbb{1}\{z_t = 1\} - \sum a_t \mathbb{1}\{z_t = 0\}}$$



A perspective on the proposed assumptions:

We have an analogue of Robins's g-formula:

$$\begin{aligned}\mu_\beta(\bar{a}) &= \mathbb{E}(Y_{\bar{a}}) = \\ &\int \mathbb{E}(Y \mid \bar{A} = \bar{a}, \bar{L} = \bar{l}, \bar{U} = \bar{u}) \times \\ &\quad \prod_j f_{L_j, U_j \mid \bar{A}_{j-1}, \bar{L}_{j-1}, \bar{U}_{j-1}}(l_j, u_j \mid \bar{a}_{j-1}, \bar{l}_{j-1}, \bar{u}_{j-1}) d\nu(l_j, u_j)\end{aligned}$$

$$0 = \int (\mathbb{E}(Y \mid \bar{A}, \bar{L}, \bar{U}) - \mu_\beta(\bar{A})) \prod_j f_{L_j, U_j \mid \bar{A}_{j-1}, \bar{L}_{j-1}, \bar{U}_{j-1}}(l_j, u_j \mid \bar{a}_{j-1}, \bar{l}_{j-1}, \bar{u}_{j-1}) d\nu(l_j, u_j)$$

Decompose the error as

$$Y - \mu_\beta(\bar{A}) = \underbrace{Y - E(Y \mid \bar{A}, \bar{Z}, \bar{L}, \bar{U})}_{\text{exogenous}} + \underbrace{E(Y \mid \bar{A}, \bar{Z}, \bar{L}, \bar{U}) - \mu_\beta(\bar{A})}_{\text{"}\eta\text{"}, \text{endogenous}}$$

Using the “g-formula” analogue,

$$\begin{aligned} \eta &= \sum_{\bar{a}} \mathbb{1}\{\bar{A} = \bar{a}\} \sum_{t=1}^T \phi_t^{(\bar{a})}(\bar{A}_{t-1}, \bar{L}_t) - \mathbb{E} \left(\phi_t^{(\bar{a})}(\bar{A}_{t-1}, \bar{L}_t) \mid \bar{A}_{t-1}, \bar{L}_{t-1} \right) \\ &= \sum_{\bar{a}} \mathbb{1}\{\bar{A} = \bar{a}\} M^{(\bar{a})} \end{aligned}$$

for some $\phi_t^{(\bar{a})}$, a sum of martingales at each level of A

We seek functions of the observed data $w(\bar{A}, \bar{L}, \bar{Z})$ to form estimating equations

$$\mathbb{E}(w(\bar{A}, \bar{L}, \bar{Z}) \times (Y - \mu_{\beta}(\bar{A}))) = \mathbb{E}(w(\bar{A}, \bar{L}, \bar{Z}) \times \eta) = 0$$

We could treat this as an IV problem (η and A are dependent), simply requiring a random variable Z orthogonal to η

But we know more about the structure of η .

Under the proposed conditions the quantities $1/\overline{W}$ are orthogonal to η

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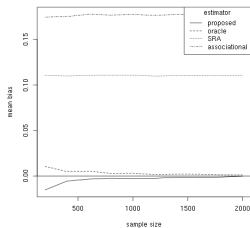
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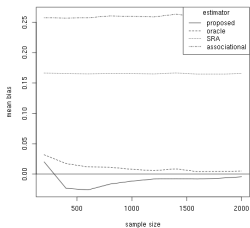
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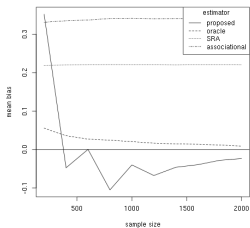
“Independent compliance type” assumption holds, “independent causal effect” does not hold



J=2

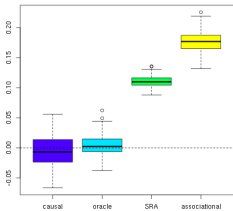


J=3

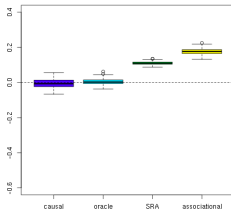


J=4

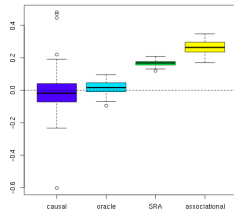
Mean bias versus sample size of the weighted estimator, for $J=2, 3,$ and $4,$ time points, compared with oracle (weights including observed and unobserved confounders), SRA (weights including observed confounders), and associational (no weighting) estimators.



J=2



J=2 (axis rescaled)



J=3

N=500

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target application: SMART trials

see Wharton tech report (Tchetgen Tchetgen, Michael, Cui '18)
for

- ▶ identification of the parameters of any marginal structural models, e.g., failure time model or quantile model
- ▶ semiparametric efficient, multiply robust estimator partially protects against model misspecification in that the estimator is consistent whenever any one of three sets of nuisance parameters are consistently estimated

References



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